

# **Integrality gap for the bin-packing problem**

**Gennady Shmonin**

Ecole Polytechnique Fédérale de Lausanne, Switzerland

Joint work with

**András Sebő**

Laboratoire G-SCOP, Grenoble, France

## Outline

- ▶ Introduction
  - ▶ Bin-packing vs. Stock-cutting
- ▶ Integer programming formulations
  - ▶ Kantorovich' assignment formulation
  - ▶ Gilmore–Gomory formulation
  - ▶ **Polynomial-size formulations**
- ▶ Integrality gaps

## The bin-packing problem

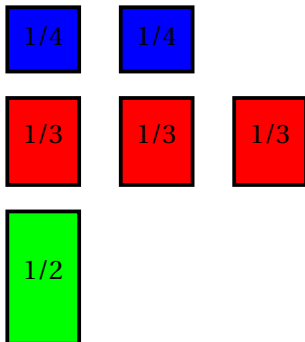
**Given**  $n$  items of sizes  $s_1, s_2, \dots, s_n$

**Find** min #bins of capacity 1 needed to pack all items

## The bin-packing problem

**Given**  $n$  items of sizes  $s_1, s_2, \dots, s_n$

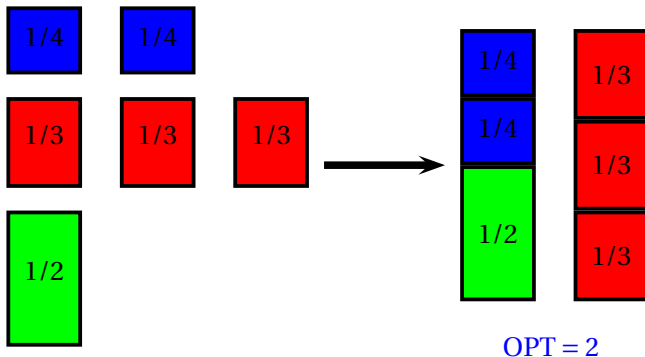
**Find** min #bins of capacity 1 needed to pack all items



## The bin-packing problem

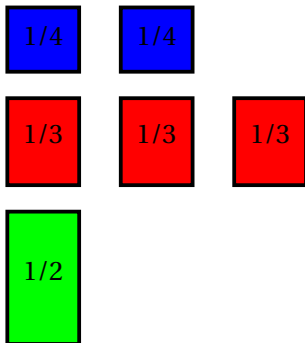
**Given**  $n$  items of sizes  $s_1, s_2, \dots, s_n$

**Find** min #bins of capacity 1 needed to pack all items



## **The stock-cutting problem**

## The stock-cutting problem



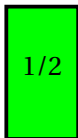
## The stock-cutting problem



$$a_1 = 1/4, b_1 = 2$$



$$a_2 = 1/3, b_2 = 3$$



$$a_3 = 1/2, b_3 = 1$$



## The stock-cutting problem



1/4



1/4

$$a_1 = 1/4, b_1 = 2$$



1/3

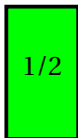


1/3



1/3

$$a_2 = 1/3, b_2 = 3$$



1/2

$$a_3 = 1/2, b_3 = 1$$

**Given** a size-vector  $a \in [0, 1]^d$  and a multiplicity-vector  $b \in \mathbb{Z}_+^d$

**Find** min #bins of capacity 1 needed to pack all items

## **Cutting stock vs. Bin packing**

In principle, the problems are equivalent

## Cutting stock vs. Bin packing

In principle, the problems are equivalent

**BUT:**

- ▶ **polynomial-time algorithm** for the bin-packing problem **is not** necessarily polynomial-time for the stock-cutting problem!
- ▶ **polynomial-size formulation** for the bin-packing problem **is not** necessarily polynomial-size for the stock-cutting problem!

## Cutting stock vs. Bin packing

In principle, the problems are equivalent

**BUT:**

- ▶ **polynomial-time algorithm** for the bin-packing problem **is not** necessarily polynomial-time for the stock-cutting problem!
- ▶ **polynomial-size formulation** for the bin-packing problem **is not** necessarily polynomial-size for the stock-cutting problem!

**Reason:**

- ▶ **Size of the input** for the stock-cutting problem is **exponentially small** compared to the input for the bin-packing problem

## Kantorovich formulation

Items:  $s_1, s_2, \dots, s_n$

Bins:  $B_1, B_2, \dots, B_n$

### Variables

- ▶  $y_j \in \{0, 1\}$  : bin  $B_j$  is open
- ▶  $x_{ij} \in \{0, 1\}$  : item  $s_i$  assigned to bin  $B_j$

### Objective

- ▶ minimize  $\sum_j y_j$  (open as few bins as possible)

### Constraints

- ▶  $x_{ij} \leq y_j$  : put items only to open bins
- ▶  $\sum_j x_{ij} = 1$  : each item is assigned to exactly one bin
- ▶  $\sum_i s_i x_{ij} \leq 1$  : capacity constraints

## Kantorovich formulation

Vectors:  $a = [a_1, a_2, \dots, a_d]$  and  $b = [b_1, b_2, \dots, b_d]$

Bins:  $B_1, B_2, \dots, B_n$

### Variables

- ▶  $y_j \in \{0, 1\}$  : bin  $B_j$  is open
- ▶  $x_{ij} \in \{0, 1, \dots, b_i\}$  : # items of type  $i$  assigned to bin  $B_j$

### Objective

- ▶ minimize  $\sum_j y_j$  (open as few bins as possible)

### Constraints

- ▶  $x_{ij} \leq b_i y_j$  : put items only to open bins
- ▶  $\sum_j x_{ij} = b_i$  : exactly  $b_i$  items of type  $i$  are assigned to bins
- ▶  $\sum_i s_i x_{ij} \leq 1$  : capacity constraints

## Kantorovich formulation

Vectors:  $a = [a_1, a_2, \dots, a_d]$  and  $b = [b_1, b_2, \dots, b_d]$

Bins:  $B_1, B_2, \dots, B_n$  ( $n = \sum_i b_i$ )

### Variables

- ▶  $y_j \in \{0, 1\}$  : bin  $B_j$  is open
- ▶  $x_{ij} \in \{0, 1, \dots, b_i\}$  : # items of type  $i$  assigned to bin  $B_j$

### Objective

- ▶ minimize  $\sum_j y_j$  (open as few bins as possible)

### Constraints

- ▶  $x_{ij} \leq b_i y_j$  : put items only to open bins
- ▶  $\sum_j x_{ij} = b_i$  : exactly  $b_i$  items of type  $i$  are assigned to bins
- ▶  $\sum_i s_i x_{ij} \leq 1$  : capacity constraints

## **Kantorovich formulation**

### **Advantages:**

- ▶ looks quite natural, easy to come up with



## **Kantorovich formulation**

### **Advantages:**

- ▶ looks quite natural, easy to come up with

### **Disadvantages:**

- ▶ **exponential-size** for **stock-cutting**

## **Kantorovich formulation**

### **Advantages:**

- ▶ looks quite natural, easy to come up with

### **Disadvantages:**

- ▶ **exponential-size** for **stock-cutting**
- ▶ moreover, even the **optimum solution** itself for stock-cutting has **exponentially many** nonzero components

## Kantorovich formulation

### Advantages:

- ▶ looks quite natural, easy to come up with

### Disadvantages:

- ▶ **exponential-size** for **stock-cutting**
- ▶ moreover, even the **optimum solution** itself for stock-cutting has **exponentially many** nonzero components
- ▶ very bad **LP relaxation**:  
 $(\text{opt}) - (\text{opt of LP relaxation})$  can be  $\approx n/2$

$\Rightarrow$  absolutely impractical

## **Gilmore–Gomory formulation**

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

## Gilmore–Gomory formulation

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

**Pattern** : “a way to pack a bin”

vector  $v \in \mathbb{Z}_+^d$  such that  $\sum_i a_i v_i \leq 1$

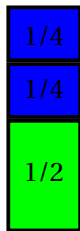
## Gilmore–Gomory formulation

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

**Pattern** : “a way to pack a bin”

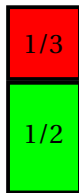
vector  $v \in \mathbb{Z}_+^d$  such that  $\sum_i a_i v_i \leq 1$



$[1, 0, 2]$



$[0, 3, 0]$



$[1, 1, 0]$

## Gilmore–Gomory formulation

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

All possible patterns:  $v_1, v_2, \dots, v_k$

### Variables

- ▶  $\lambda_j \in \mathbb{Z}_+$  : # pattern  $v_j$  to be used in the packing

### Objective

- ▶ minimize  $\sum_j \lambda_j$  : total # patterns = total # bins

### Constraints

- ▶  $\sum_j \lambda_j v_{ij} = b_i$  : all items of type  $i$  are packed  
equiv.  $\sum_j \lambda_j v_j = b$

## Gilmore–Gomory formulation

$$\begin{aligned} \min \quad & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{aligned}$$

### Disadvantages:

- ▶ **exponential-size** for both **bin-packing** and **stock-cutting** (in fact, much larger than that of Kantorovich)



## Gilmore–Gomory formulation

$$\begin{aligned} \min \quad & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{aligned}$$

### Disadvantages:

- ▶ **exponential-size** for both **bin-packing** and **stock-cutting** (in fact, much larger than that of Kantorovich)

### Advantages:

- ▶ there is an **optimum solution** with **polynomially many** nonzero components (Eisenbrand & S. 2006)

## Gilmore–Gomory formulation

$$\begin{array}{ll} \min & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{array}$$

### Disadvantages:

- ▶ **exponential-size** for both **bin-packing** and **stock-cutting** (in fact, much larger than that of Kantorovich)

### Advantages:

- ▶ there is an **optimum solution** with **polynomially many** nonzero components (Eisenbrand & S. 2006)
- ▶ **very strong LP relaxation**

## Gilmore–Gomory formulation

$$\begin{aligned} \min \quad & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{aligned}$$

### Disadvantages:

- ▶ **exponential-size** for both **bin-packing** and **stock-cutting** (in fact, much larger than that of Kantorovich)

### Advantages:

- ▶ there is an **optimum solution** with **polynomially many** nonzero components (Eisenbrand & S. 2006)
- ▶ **very strong LP relaxation**
- ▶ **column-generation methods** help to deal with “exponential size issue”

## Gilmore–Gomory formulation

$$\begin{aligned} \min \quad & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{aligned}$$

### Disadvantages:

- ▶ **exponential-size** for both **bin-packing** and **stock-cutting** (in fact, much larger than that of Kantorovich)

### Advantages:

- ▶ there is an **optimum solution** with **polynomially many** nonzero components (Eisenbrand & S. 2006)
- ▶ **very strong LP relaxation** ???
- ▶ **column-generation methods** help to deal with “exponential size issue”

## Subpattern formulation

(Belov & Weismantel 2004)

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

**Subpattern** :  $u_{ik} = 2^k e_i$

- ▶ polynomially many subpatterns
- ▶ each pattern  $v$  can be expressed as

$$v = \sum_{i,k} \mu_{ik} u_{ik} \text{ with } \mu_{ik} \in \{0, 1\}$$

**Idea:** rewrite Gilmore–Gomory formulation in terms of subpatterns

$$b = \sum_j \lambda_j v_j \quad \longrightarrow \quad b = \sum_{i,j,k} \lambda_j \mu_{jik} u_{ik} = \sum_{i,j,k} \eta_{jik} u_{ik}$$

## Subpattern formulation

(Belov & Weismantel 2004)

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

Subpatterns:  $u_{ik} = 2^k e_i$

$v_1, v_2, \dots, v_t$  : patterns to be used in a solution (unknowns!)

### Variables

- ▶  $\lambda_j \in \mathbb{Z}_+$  : # patterns  $v_j$  to be used in the packing
- ▶  $\mu_{jik} \in \{0, 1\}$  : coefficients to express pattern  $v_j$
- ▶  $\eta_{jik} \in \mathbb{Z}_+$  : (“switch”)  $\eta_{jik} = \lambda_j$  if  $\mu_{jik} = 1$ ;  $\eta_{jik} = 0$  otherwise

### Objective

- ▶ minimize  $\sum_{j=1}^t \lambda_j$

## Subpattern formulation

(Belov & Weismantel 2004)

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

Subpatterns:  $u_{ik} = 2^k e_i$

$v_1, v_2, \dots, v_t$ : patterns to be used in a solution (unknowns!)

### Constraints

- ▶  $\sum_{i,j,k} \eta_{jik} u_{ij} = b$ : all items are packed
- ▶  $\sum_{i,k} \mu_{jik} a^T u_{ij} \leq 1$ : capacity constraint
- ▶  $\lambda_j \geq \eta_{jik}$
- ▶  $\eta_{jik} \leq M \cdot \mu_{jik}$  (for  $M$  sufficiently large)

## Another polynomial-size formulation

$$\begin{aligned} \min \quad & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{aligned}$$

Let  $\lambda_1, \lambda_2, \dots, \lambda_t$  be optimum solution,  $b = \sum_j \lambda_j v_j$

Only polynomially many (say  $m$  nonzeros)

$\implies$  for some pattern  $v_j$  the coefficient  $\lambda_j \geq \text{OPT}/m$

$\implies b = \frac{\text{OPT}}{m} v + b'$  (where  $v$  is **unknown**)

Inductively, we obtain

$$b = \sum_j \lambda_j^* v_j,$$

where  $v_j \in \mathbb{Z}_+^d$ 's are **unknown patterns** and  $\lambda_j^*$  are **numbers**



## Integrality gap

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

All possible patterns:  $v_1, v_2, \dots, v_k$

### Gilmore–Gomory formulation

$$\begin{aligned} \min \quad & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{aligned}$$

$\text{OPT}(a, b)$  : optimum value

$\text{LIN}(a, b)$  : optimum value of LP relaxation

$\text{SIZE}(a, b) = a^T b$  : total size

## Integrality gap

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

All possible patterns:  $v_1, v_2, \dots, v_k$

$$\begin{aligned} \min \quad & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{aligned}$$

- ▶ vast majority of the instances have “integer round-up property”

$$\text{OPT}(a, b) = \lceil \text{LIN}(a, b) \rceil$$

- ▶ no instance is known to violate “modified integer round-up property”

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

## Integrality gap

**Conjecture** [Scheithauer & Terno 1996]

For all  $a \in [0, 1]^d$  and  $b \in \mathbb{Z}_+^d$ ,

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

## Integrality gap

### Conjecture [Scheithauer & Terno 1996]

For all  $a \in [0, 1]^d$  and  $b \in \mathbb{Z}_+^d$ ,

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

### Theorem [Scheithauer & Terno 1996]

For all  $a \in [0, 1]^6$  and  $b \in \mathbb{Z}_+^6$ ,

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

## Integrality gap

**Conjecture** [Scheithauer & Terno 1996]

For all  $a \in [0, 1]^d$  and  $b \in \mathbb{Z}_+^d$ ,

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

**Theorem** [Scheithauer & Terno 1996]

For all  $a \in [0, 1]^6$  and  $b \in \mathbb{Z}_+^6$ ,

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

**Theorem** [Karmarkar & Karp 1982]

For all  $a \in [0, 1]^d$  and  $b \in \mathbb{Z}_+^d$ ,

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + O(\log^2 d)$$

## Integrality gap

### Theorem

For all  $a \in [0, 1]^7$  and  $b \in \mathbb{Z}_+^7$ ,

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

## Sketch of the proof

### Residual instances

There is an optimum solution of **LP relaxation** with at most  $d$  nonzero components:

$$\text{LIN}(a, b) = \sum_{i=1}^d \lambda_i \quad \text{and} \quad b = \sum_{i=1}^d \lambda_i v_i$$

**Residual instance** : defined  $a$  and  $b' = \sum_{i=1}^d \{\lambda_i\} v_i$

$$\text{OPT}(a, b) \leq \text{OPT}(a, b') + \sum_{i=1}^d \lfloor \lambda_i \rfloor$$

$$\text{LIN}(a, b) = \text{LIN}(a, b') + \sum_{i=1}^d \lfloor \lambda_i \rfloor$$

$$\Rightarrow \text{OPT}(a, b') - \lfloor \text{LIN}(a, b') \rfloor \geq \text{OPT}(a, b) - \lfloor \text{LIN}(a, b) \rfloor$$

## Sketch of the proof

### Small items

Suppose  $a_1 < \frac{1}{\text{SIZE}(a,b)}$

Consider instance given by

size-vector  $a' = [a_2, a_3, \dots, a_d]$

multiplicity-vector  $b' = [b_2, b_3, \dots, b_d]$

### Algorithm

- (1) Find  $\text{OPT}(a', b')$
- (2) Pack items of type 1 greedily

$\Rightarrow$  either  $\text{OPT}(a, b) - \lceil \text{LIN}(a, b) \rceil \leq \text{OPT}(a', b') - \lceil \text{LIN}(a', b') \rceil$

or  $\text{OPT}(a, b) - \lceil \text{LIN}(a, b) \rceil \leq 1$



## Sketch of the proof

### Corollary

For all  $a \in [0, 1]^d$  and  $b \in \mathbb{Z}_+^d$ ,

if  $1/a_i \in \mathbb{Z}$  ( $i = 1, 2, \dots, d$ ), then

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

## Sketch of the proof

### Corollary

For all  $a \in [0, 1]^d$  and  $b \in \mathbb{Z}_+^d$ ,

if  $1/a_i \in \mathbb{Z}$  ( $i = 1, 2, \dots, d$ ), then

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

Explore the **minimal counter-example**:

- ▶ w.l.o.g., **residual instance**  $\implies \text{OPT}(a, b) \leq d$
- ▶ w.l.o.g., **no small items**  $\implies a_i > \frac{1}{\text{SIZE}(a, b)} \geq \frac{1}{\text{OPT}(a, b)} \geq \frac{1}{d}$

## Sketch of the proof

### Corollary

For all  $a \in [0, 1]^d$  and  $b \in \mathbb{Z}_+^d$ ,

if  $1/a_i \in \mathbb{Z}$  ( $i = 1, 2, \dots, d$ ), then

$$\text{OPT}(a, b) \leq \lceil \text{LIN}(a, b) \rceil + 1$$

Explore the **minimal counter-example**:

- ▶ w.l.o.g., **residual instance**  $\implies \text{OPT}(a, b) \leq d$
- ▶ w.l.o.g., **no small items**  $\implies a_i > \frac{1}{\text{SIZE}(a, b)} \geq \frac{1}{\text{OPT}(a, b)} \geq \frac{1}{d}$

$$1, \frac{1}{2}, \frac{1}{3}, \dots, \frac{1}{d} \dots \text{oops}$$

## Sketch of the proof

### Duality

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

All possible patterns:  $v_1, v_2, \dots, v_k$

$$\begin{array}{ll} \min & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{array}$$

Optimum solution:  $b = u_1 + u_2 + \dots + u_{m+1}$

## Sketch of the proof

### Duality

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

All possible patterns:  $v_1, v_2, \dots, v_k$

$$\begin{aligned} \min \quad & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{aligned}$$

Optimum solution:  $b = u_1 + u_2 + \dots + u_{m+1}$

Assign **weights**  $w_1, w_2, \dots, w_d$

- ▶  $w^T v \leq 1$  whenever  $a^T v \leq 1$ 
  - $\implies$  “patterns remain patterns”
  - $\implies \text{LIN}(w, b) \geq \text{LIN}(a, b)$
- ▶  $w^T b > m - 1$

## Sketch of the proof

### Duality

Size-vectors:  $a = [a_1, a_2, \dots, a_d]$

Multiplicity-vector:  $b = [b_1, b_2, \dots, b_d]$

All possible patterns:  $v_1, v_2, \dots, v_k$

$$\begin{aligned} \min \quad & \sum_j \lambda_j \\ & \sum_j \lambda_j v_j = b \\ & \lambda_j \geq 0 \text{ integer} \end{aligned}$$

Optimum solution:  $b = u_1 + u_2 + \dots + u_{m+1}$

Assign **weights**  $w_1, w_2, \dots, w_d$

- ▶  $w^T v \leq 1$  whenever  $a^T v \leq 1$ 
  - $\implies$  “patterns remain patterns”
  - $\implies \text{LIN}(w, b) \geq \text{LIN}(a, b)$
- ▶  $w^T b > m - 1 \implies$  **not a counter-example!**

## **Sketch of the proof**

**Case  $d \leq 7$**

## Sketch of the proof

Case  $d \leq 7$

By **Residual instances**: need to check  $[\text{LIN}(a, b)] = 1, 2, 3, 4, 5, 6, 7$



## Sketch of the proof

Case  $d \leq 7$

By **Residual instances**: need to check  $\lceil \text{LIN}(a, b) \rceil = 1, 2, 3, 4, 5, 6, 7$

Suppose  $\text{LIN}(a, b) = 4$

## Sketch of the proof

Case  $d \leq 7$

By **Residual instances**: need to check  $\lceil \text{LIN}(a, b) \rceil = 1, 2, 3, 4, 5, 6, 7$

Suppose  $\text{LIN}(a, b) = 4$

By **Small items**: all items are bigger than  $1/3$

## Sketch of the proof

Case  $d \leq 7$

By **Residual instances**: need to check  $\lceil \text{LIN}(a, b) \rceil = 1, 2, 3, 4, 5, 6, 7$

Suppose  $\text{LIN}(a, b) = 4$

By **Small items**: all items are bigger than  $1/3$

**Optimum packing:**  $b = u_1 + u_2 + u_3 + u_4 + R$

- ▶ either  $\|u_i\|_1 = 1$  or  $\|u_i\|_1 = 2$
- ▶  $\|R\|_1 = 3$  and  $R$  contains the **smallest item**

## Sketch of the proof

Case  $d \leq 7$

By **Residual instances**: need to check  $\lceil \text{LIN}(a, b) \rceil = 1, 2, 3, 4, 5, 6, 7$

Suppose  $\text{LIN}(a, b) = 4$

By **Small items**: all items are bigger than  $1/3$

**Optimum packing:**  $b = u_1 + u_2 + u_3 + u_4 + R$

- ▶ either  $\|u_i\|_1 = 1$  or  $\|u_i\|_1 = 2$
- ▶  $\|R\|_1 = 3$  and  $R$  contains the **smallest item**

**Weights:**

1 for items in 1-bins

$1/2$  for items in 2-bins and **largest** item in  $R$

## Open problems

- ▶ **Polynomial-time algorithm** when  $d$  is fixed
  - ▶  $d = 2$ : McCormick, Smallwood, Spieksma (2001)
  - ▶  $d = 3$ : **open**
- ▶ **Integrality gap** for  $d \geq 8$ ?
- ▶ **Approximation** “+1”-algorithm?

$$\mathcal{A}(a, b) \leq \text{OPT}(a, b) + 1$$

Thank You for Your attention!