# Modeling Communications in Current Platforms Master 2 Research Lecture: Parallel Systems

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# Motivation

- Scientific computing : large needs in computation or storage resources.
- ▶ Need to use systems with "several processors":
  - Parallel computers with shared/distributed memory
  - Clusters
  - Heterogeneous clusters

- Clusters of clusters
- Network of workstations
- The Grid
- Desktop Grids
- When modeling platform, communications modeling seems to be the most controversial part.
- Two kinds of people produce communication models: those who are concerned with scheduling and those who are concerned with performance evaluation.
- ► All these models are imperfect and intractable.



### 2 Point to Point Communication Models

- Hockney
- LogP and Friends
- TCP

### 3 Modeling Concurency

- Multi-port
- Single-port (Pure and Full Duplex)
- Flows

#### 4 Remind This is a Model, Hence Imperfect

## Outline

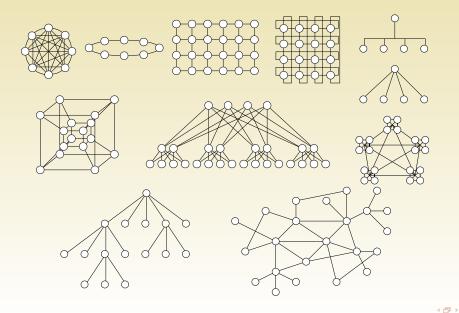


Point to Point Communication Models
Hockney
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# Various Topologies Used in the Litterature



## Topology

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Hem... This one is mainly used by scheduling theoreticians to prove that their problem is hard and to know whether there is some hope to prove some clever result or not.

# "Hockney" Model

Hockney [Hoc94] proposed the following model for performance evaluation of the Paragon. A message of size m from  $P_i$  to  $P_j$  requires:

$$t_{i,j}(m) = L_{i,j} + m/B_{i,j}$$

In scheduling, there are three types of "corresponding" models:

- Communications are not "splitable" and each communication k is associated to a communication time t<sub>k</sub> (accounting for message size, latency, bandwidth, middleware, ...).
- Communications are "splitable" but latency is considered to be negligible (linear divisible model):

$$t_{i,j}(m) = m/B_{i,j}$$

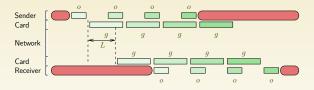
Communications are "splitable" and latency cannot be neglected (linear divisible model):

$$t_{i,j}(m) = L_{i,j} + m/B_{i,j}$$

# LogF

#### The LogP model $[CKP^+96]$ is defined by 4 parameters:

- L is the network latency
- o is the middleware overhead (message splitting and packing, buffer management, connection,  $\ldots$ ) for a message of size w
- q is the gap (the minimum time between two packets communication) between two messages of size w
- P is the number of processors/modules



Sending m bytes with packets of size w:

$$2o + L + \left\lceil \frac{m}{w} \right\rceil \cdot \max(o, g)$$

Occupation on the sender and on the receiver:

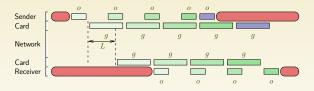
$$p + L + \left( \left\lceil \frac{m}{w} \right\rceil - 1 \right) \cdot \max(o, g)$$

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The previous model works fine for short messages. However, many parallel machines have special support for long messages, hence a higher bandwidth. LogGP [AISS97] is an extension of LogP: G captures the bandwidth for long messages:

short messages  $2o + L + \left\lceil \frac{m}{w} \right\rceil \cdot \max(o, g)$ 

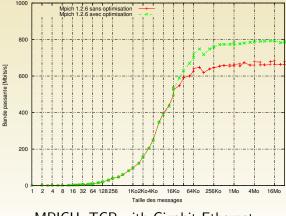
long messages 
$$2o + L + (m-1)G$$

There is no fundamental difference...

OK, it works for small and large messages. Does it work for averagesize messages ? pLogP [KBV00] is an extension of LogP when L, oand g depends on the message size m. They also have introduced a distinction between  $o_s$  and  $o_r$ . This is more and more precise but concurrency is still not taken into account.

## Bandwidth as a Function of Message Size

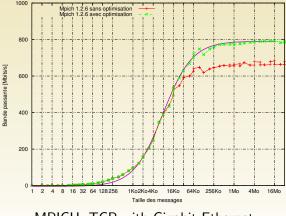
With the Hockney model:  $\frac{m}{L+m/B}$ .



MPICH, TCP with Gigabit Ethernet

## Bandwidth as a Function of Message Size

With the Hockney model:  $\frac{m}{L+m/B}$ .



MPICH, TCP with Gigabit Ethernet

The previous models work fine for parallel machines. Most networks use TCP that has fancy flow-control mechanism and slow start. Is it valid to use affine model for such networks?

The answer seems to be yes but latency and bandwidth parameters have to be carefully measured [LQDB05].

- Probing for m = 1b and m = 1Mb leads to bad results.
- The whole middleware layers should be benchmarked (theoretical latency is useless because of middleware, theoretical bandwidth is useless because of middleware and latency).

The slow-start does not seem to be too harmful. Most people forget that the round-trip time has a huge impact on the bandwidth.

## Topology

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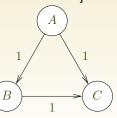
# Multi-ports

- A given processor can communicate with as many other processors as he wishes without any degradation.
- This model is widely used by scheduling theoreticians (think about all DAG with communications scheduling problems) to prove that their problem is hard and to know whether there is some hope to prove some clever result or not.

Some theoreticians feel like this model is borderline, especially when allowing duplication or when trying to design algorithms with super tight approximation ratios [Yves Robert 01–??].

Frankly, such a model is totally unrealistic.

Using MPI and synchronous communications, it may not be an issue. However, with multi-core, multi-processor machines, it cannot be ignored...

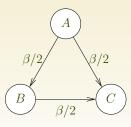


Multi-port

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# Bounded Multi-port

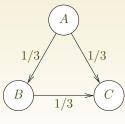
- Assume now that we have threads or multi-core processors. We can write that sum of the throughputs of all communications (incomming and outgoing). Such a model is OK for wide-area communications [HP04].
- Remember, the bounds due to the round-trip-time must not be forgotten!



Multi-port ( $\beta$ )

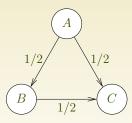
# Single-port (Pure)

- A process can communicate with only one other process at a time. This constraint is generally written as a constraint on the sum of communication times and is thus rather easy to use in a scheduling context (even though it complexifies problems).
- This model makes sense when using non-threaded versions of communication libraries (e.g., MPI). As soon as you're allowed to use threads, bounded-multiport seems a more reasonnable option (both for performance and scheduling complexity).



1-port (pure)

At a given time, a process can be engaged in at most one emission and one reception. This constraint is generally written as two constraints: one on the sum of incomming communication times and one on the sum of outgoing communication times.

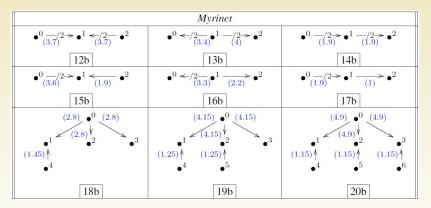


1-port (full duplex)

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# Single-port (Full-Duplex)

This model somehow makes sense when using networks like Myrinet that have few multiplexing units and with protocols without control flow [Mar07].

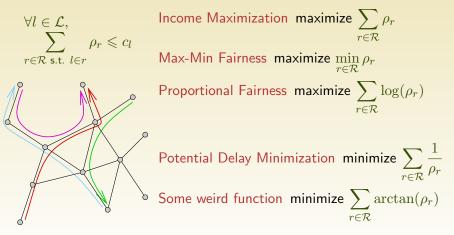


Even if it does not model well complex situations, such a model is not harmfull.

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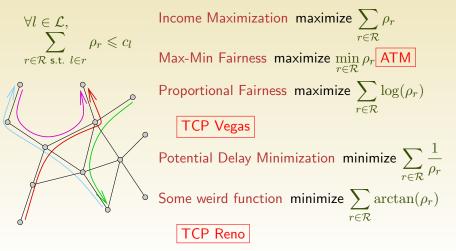
# Fluid Modeling

When using TCP-based networks, it is generally reasonnable to use flows to model bandwidth sharing [MR99, Low03].



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- Note that this model is a multi-port model with capacity-constraints (like in the previous bounded multi-port).
- When latencies are large, using multiple connections enables to get more bandwidth. As a matter of fact, there is very few to loose in using multiple connections...
- Therefore many people enforce a sometimes artificial (but less intrusive) bound on the maximum number of connections per link [Wag05, MYCR06].

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# Remind This is a Model, Hence Imperfect

- The previous sharing models are nice but you generally do not know other flows...
- Communications use the memory bus and hence interfere with computations. Taking such interferences into account may become more and more important with multi-core architectures.
- Interference between communications are sometimes... surprising.

Modeling is an art. You have to know your platform and your application to know what is negligeable and what is important. Even if your model is imperfect, you may still derive interesting results.

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