Homogeneous versus hierarchical communication delay model:complexity and approximation

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- Simplicity of the model
- Not specified for a particular machine

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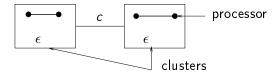
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If c_{ii} = 0, \forall (i,j) \in E then we have the model without
communication (PRAM model)
```

Multi-core assumption

An investigation of the scheduling problem from a application on the parallel machine constituted by a set of clusters of processors. To require taking account hierarchical communication.

- intra-clusters (denoted by ϵ_{ii})
- extra-clusters (denoted by c_{ij})



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- Heterogeneous or Homogeneous processors

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 - Only one processor per cluster, m=1
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 - $\forall (i,j) \in E, c_{ii} = \epsilon_{ii}$

$$ar{P}| extit{prec}\,, c_{ij}=c\geq 1; p_i=1|C_{ extit{max}}$$
 where

Using the three fields $\alpha |\beta| \gamma$ a schedule problem in Homogeneous model can be denoted in what follows :

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$$ar{P}(Pl \geq 2)|prec;(c_{ij},\epsilon_{ij}) = (c,c'); p_i = 1|C_{max}$$
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As the same as previously, a schedule problem in Hierarchical model can be denoted in what follows :

$$ar{P}(Pl \geq 2)| extit{prec}; (c_{ij}, \epsilon_{ij}) = (c, c'); p_i = 1|C_{ extit{max}}$$
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• $\bar{P}(Pl \ge 2)$ signify unbounded number of clusters with at most two processors

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- Polynomial-time approximation algorithms are existed according to the type of precedence graph (independent tasks, chains, trees, general precedence graphs) [Trystram, Mounie, Rapine, Dutot]

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- Theoretical aspect of scheduling problems
- Upper bounds (Positives results)
- Lower bounds (Negatives results)

Homogeneous model: Negative result (1)

- $\bullet \forall i \in V, p_i = 1, \forall (i,j) \in E, c_{ii} = 1$
- Unbounded number of processors

$$\frac{\#}{\rho}$$
 -approximation with $\rho < \frac{7}{6}$, unless $\mathcal{P} = \mathcal{NP}$ [Hoogeveen,Lenstra,Veltman 94]

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$$\frac{1}{2} \rho$$
 -approximation with $\rho < \frac{5}{4}$, unless $\mathcal{P} = \mathcal{N}\mathcal{P}$ [Hoogeveen,Lenstra,Veltman 94]



Homogeneous model: Negative result (2)

- $\forall i \in V, p_i = 1, \forall (i,j) \in E, c_{ij} = c \geq 2$
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$$exists
ho$$
-approximation with $ho < 1 + rac{1}{c+3}$, unless $\mathcal{P} = \mathcal{NP}$ [Bampis,Giannakos,König96]

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Hierarchical model : Negative result (1)

- $\forall i \in V, p_i = 1, \forall (i,j) \in E, c_{ij} = 1 \text{ and } \epsilon_{ij} = 0$
- Unbounded number of clusters, 2 identical processors per cluster
- $\bar{P}(P_2)|prec;(c_{ij},\epsilon_{ij})=(1,0);p_i=1|C_{max}$

 $\frac{1}{2}$ ρ -approximation with $\rho < \frac{5}{4}$, unless if $\mathcal{P} = \mathcal{N}\mathcal{P}$ [Bampis,Giroudeau,König 99]

Hierarchical model : Negative result (2)

- $\forall i \in V, p_i = 1, \forall (i,j) \in E, c_{ij} = 2 \text{ and } \epsilon_{ij} = 1$
- Unbounded number of clusters, 2 identical processors per cluster
- $\frac{\pi}{2}$ ρ -approximation with $\rho < \frac{6}{5}$, unless if $\mathcal{P} = \mathcal{N}\mathcal{P}$ [Giroudeau 04]
- $\forall i \in V, p_i = 1, \forall (i,j) \in E, c_{ij} = c$ and $\epsilon_{ij} = c'$ with $c \geq c'$
- Unbounded number of clusters, $m \ge 2$ identical processors per cluster
 - \nexists $\rho\text{-approximation}$ with $\rho<1+\frac{1}{c+3},$ unless if $\mathcal{P}=\mathcal{NP}$ [Giroudeau,König 04]



Complexity results

Number of processors	Com. Delay (c_{ij}, ϵ_{ij})	Complexity
P	(1,1)	$ ho \geq \frac{7}{6}$
P	(c,c)	$ \rho \geq \frac{c+5}{c+4} $
Р	(1,1)	$\rho \geq \frac{4}{3}$
Р	(c,c)	$ \rho \geq \frac{c+4}{c+3} $
$\bar{P}(P_2)$	(1,0)	$ ho \geq \frac{4}{3}$
$\bar{P}(P_2)$	$(c,c'), \ c>c'\geq 1$	$ \rho \ge \frac{c+4}{c+3} $
$P(P_2)$ bipartite	(1, 1)	$ ho \geq \frac{4}{3}$

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A lower bound implies that there is non \mathcal{PTAS} for all previous scheduling problems

Homogeneous model: Positive result

• $\exists \frac{4}{3}$ -approximation algorithm for the problem $\bar{P}|p_i=1, c_{ij}=1|C_{max}$ [Munier,König 97]

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- $\exists \frac{4}{3}$ -approximation algorithm for the problem $ar{P}|p_i=1,c_{ij}=1|\mathit{C}_{max}$ [Munier,König 97]
- Integer Linear Programming Formulation

$$PL_{I} \begin{tabular}{l} \textbf{MinC}_{max} \\ \forall (i,j) \in E, & x_{ij} \in \{0,1\} \\ \forall i \in V, & t_{i} \geq 0 \\ \forall (i,j) \in E, & t_{i} + 1 + x_{ij} \leq t_{j} \\ \forall i \in V - U, & \sum_{j \in \Gamma^{+}(i)} x_{ij} \geq |\Gamma^{-}(i)| - 1 \\ \forall i \in V - Z, & \sum_{j \in \Gamma^{-}(i)} x_{ji} \geq |\Gamma^{-}(i)| - 1 \\ \forall i \in V \end{tabular}$$

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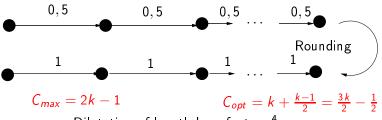
$$C_{max} \leq \frac{4}{3}C_{max}^{opt}$$



Tightness of the bound

The bound is tight:

a path with k vertices



Dilatation of length by a factor $:\frac{4}{3}$

Hierarchical model: Positive result

• $(2-\frac{2}{2m+1})$ -approximation algorithm for the problem $\bar{P}(P_m)|prec;(c_{ij},\epsilon_{ij})=(1,0);p_i=1|C_{max}$ with $m\geq 1$ [Bampis,Giroudeau,König 99]

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$$\begin{cases} \forall (i,j) \in E, & x_{ij} \in \{0,1\} \\ \forall i \in V, & t_i \geq 0 \\ \forall (i,j) \in E, & \sum_{j \in \Gamma^+(i)} x_{ij} \geq |\Gamma^+(i)| - 2 \\ \forall (i,j) \in E - U, & \sum_{j \in \Gamma^-(i)} x_{ji} \geq |\Gamma^-(i)| - 2 \\ \forall (i,j) \in E - Z, & \sum_{j \in \Gamma^-(i)} x_{ji} \geq |\Gamma^-(i)| - 2 \\ \forall (i,j), (j,k), (l,k), (l,m) \in E, & x_{ji} + x_{jk} + x_{lk} + x_{lm} \geq 1 \\ (j,i), (j,k), (l,k), (l,m) \in E, & x_{ij} + x_{kj} + x_{kl} + x_{ml} \geq 1 \\ \forall i,j, k, l, m \in V, & x_{ij} + x_{kj} + x_{kl} + x_{ml} \geq 1 \\ (i,j), (k,j), (k,l), (m,l) \in E, & t_i + 1 \leq C_{max} \end{cases}$$

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•

- An integrity constraint is relaxed $x_{ii} \in \{0,1\} \Rightarrow e_{ii} \in [0,1]$, $PL_I \Rightarrow PL_I^{inf}$
- and feasible schedule is produced by rounding

$$\begin{cases} & \text{if } e_{ij} < 0.25 \implies x_{ij} = 0 \\ & \text{if } e_{ij} \ge 0.25 \implies x_{ij} = 1 \end{cases}$$





- Another step is needed in order to get a feasible schedule
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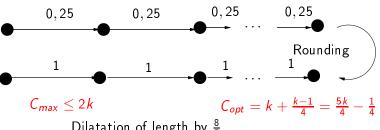
The bound is tight



Tightness of the bound

The bound is tight:

a path with k vertices



Dilatation of length by §

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- $(1+(2-\frac{1}{m})\frac{8}{5})$ -approximation algorithm for the problem $P(P_m)|prec;(c_{ij},\epsilon_{ij})=(1,0); p_i=1|C_{max}$

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- For the large communication delays $c \geq 2$ (or $(c_{ij} = c, \epsilon_{ij} = c')$ with $c > c' \geq 1$), it exists an-approximation algorithm A such that $A \in \mathcal{APX}$?

Approximation algorithm for Large communication delay in homogeneous model

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Approximation algorithm for Large communication delay in homogeneous model

- We consider the case of c > 2
- $\bar{P}|prec; c_{ij} \geq 2; p_i = 1|C_{max} \in \mathcal{APX}$?
- We develop a new algorithm based on the solution given the problem $\bar{P}|prec; c_{ij}=1; p_i=1|C_{max}$

Strategy

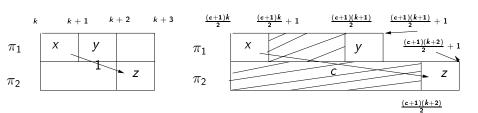
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- Third Step An expansion of the makespan, while preserving communication delays $(t_j^c \ge t_i^c + 1 + c)$ for i and j with $(i,j) \in E$, processing on two different processors



Coefficient of expansion

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- $ullet t_i^c = d imes t_i ext{ and } t_j^c = d imes t_j$
- After an expansion, $t_j^c \ge t_i^c + 1 + c$, and so $d \times t_i d \times t_j \ge c + 1$, $d \ge \frac{c+1}{t_i t_j}$, $d \ge \frac{c+1}{2} \Rightarrow d = \frac{(c+1)}{2}$

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$$\bullet \rho \le \frac{2(c+1)}{3}$$

Hierarchical model

• The previous algorithm may used to derive a polynomial-time with performance ratio equal to $\frac{(c+1)(1-\frac{1}{2m+1})}{(c+1)(p-1)} - \text{approximation algorithm for the problem } \bar{P}(P_m)|_{prec}: (c_{ii}, \epsilon_{ii}) = (c, c'); p_i = 1|C_{max} \text{ with } m \geq 1$

Approximation

# processors	Com. Delay (c_{ij}, ϵ_{ij})	Complexity & Approximation
P	(1, 1)	$\frac{7}{6} \le \rho \le \frac{4}{3}$
P	(c,c)	$\frac{c+5}{c+4} \le \rho \le \frac{2(c+1)}{3}$
Р	(1,1)	$\frac{4}{3} \le \rho \le \frac{7}{3}$
Р	(c,c)	$\frac{c+4}{c+3} \le \rho \le \frac{7(c+1)}{6}$
$\bar{P}(P_2)$	(1,0)	$\frac{4}{3} \le \rho \le \frac{8}{5}$
$\bar{P}(P_2)$	$(c,c'), \ c>c'\geq 1$	$\frac{c+4}{c+3} \le \rho \le (c+1)(1-\frac{1}{2m+1})$

Conclusion on homogeneous versus hierarchical model

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Conclusion on homogeneous versus hierarchical model

- Techniques used in polynomial-time transformations (complexity) resist to passage to hierarchical communication model
- Techniques used for approximation algorithm also resist to passage to hierarchical communication model

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 - Approximation algorithms :
 - There exists a ρ -approximation with $\rho < 4/3$ for the scheduling problem $\bar{P}|p_i=1, c_{ij}=1|C_{max}$?
 - There exists a ρ -approximation algorithm with $\rho \in \mathbb{R}$ for the scheduling problem $\bar{P}|p_i=1,c_{ij}=c\geq 2|C_{max}$?

Conclusion

Any questions?